# Operating Instructions Micropilot FMR10

Free space radar







# Table of contents

1	Document information	4
1.1 1.2	Symbols for certain types of information Safety symbols	4 4
1.3	Symbols in graphics	4
2	Terms and abbreviations	5
3	Basic safety instructions	6
3.1 3.2 3.3 3.4 3.5	Requirements for personnelDesignated useWorkplace safetyOperational safetyProduct safety3.5.1CE mark	6 7 7 7 7
4	Registered trademarks	7
5	Supplementary documentation	9
5.1	Standard documentation	9
6	Product description	10
6.1	Product design	10 10
7	Incoming acceptance and product	
	identification	11
7.1 7.2	Incoming acceptance	11 12
8	Installation	13
8.1	Installation conditions8.1.1Installation types8.1.2Nozzle installation8.1.3Orientation8.1.4Alignment8.1.5Beam angle8.1.6Measurement in plastic vessels8.1.7Weather protection cover8.1.8Free-field measurement with flooding protection tube8.1.9Installation with mounting bracket, adjustable8.1.10Cantilever installation, with pivot8.1.11Post-installation check	13 13 14 14 15 15 16 16 17 18 18
9	Electrical connection	19
9.1 9.2 9.3 9.4	Cable assignment	19 19 20 20

10	Operability	21	
10.1 10.2	Operating concept	21 21	
11	Commissioning and operation	22	
11.1 11.2 11.3	Installation and function check Operation and settings via SmartBlue (app) Configuring level measurement via operating	22 22	
11.4	software 11.3.1 Displaying level value as % Data access - Security 11.4.1 Software looking via access code in	27 28 29	
	11.4.1       Software focking via access code in SmartBlue         11.4.2       Unlocking via SmartBlue         11.4.3       Bluetooth® wireless technology	29 29 29	
12	Diagnostics and troubloshooting	30	
12.1 12.2 12.3	General trouble shooting General errors Diagnostic event	30 30 31	
12.4	List of diagnostic events	31 31	
13	Maintenance	32	
13.1 13.2	Exterior cleaning	32 32	
14	Repair	33	
14.1	General notes 14.1.1 Repair concept 14.1.2 Replacing a device 14.1.3 Return 14.1.4 Disposal	33 33 33 33 33 33	
15	Accessories	34	
15.1	Overview	34	
16	Operating menu	35	
16.1 16.2 16.3	Overview operating menue (SmartBlue)"Setup" menu16.2.1"Advanced setup" submenu16.2.2"Communication" submenu"Diagnostics" submenu16.3.1"Device information" submenu16.3.2"Simulation" submenu	35 39 42 52 53 55 57	
Index 58			

# 1 Document information

# 1.1 Symbols for certain types of information

Symbol	Meaning	
	<b>Permitted</b> Procedures, processes or actions that are permitted.	
	<b>Preferred</b> Procedures, processes or actions that are preferred.	
$\mathbf{X}$	<b>Forbidden</b> Procedures, processes or actions that are forbidden.	
i	<b>Tip</b> Indicates additional information.	
i	Reference to documentation	
	Reference to page	
	Reference to graphic	
1. , 2. , 3	Series of steps	
L <b>&gt;</b>	Result of a step	
?	Help in the event of a problem	
	Visual inspection	

# 1.2 Safety symbols

Symbol	Meaning	
	<b>DANGER!</b> This symbol alerts you to a dangerous situation. Failure to avoid this situation will result in serious or fatal injury.	
A WARNING	<b>WARNING!</b> This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in serious or fatal injury.	
	<b>CAUTION!</b> This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in minor or medium injury.	
NOTICE	<b>NOTE!</b> This symbol contains information on procedures and other facts which do not result in personal injury.	

# **1.3** Symbols in graphics

Symbol	Meaning
1, 2, 3	Item numbers
1. , 2. , 3	Series of steps
A, B, C,	Views
A-A, B-B, C-C,	Sections

Symbol	Meaning
EX	Hazardous area Indicates a hazardous area.
×	Safe area (non-hazardous area) Indicates the non-hazardous area.

# 2 Terms and abbreviations

Term/abbreviation	Explanation
ВА	Document type "Operating Instructions"
КА	Document type "Brief Operating Instructions"
TI	Technical Information
SD	Document type "Special Documentation"
ХА	Document type "Safety Instructions"
PN	Nominal pressure
MWP	Maximum Working Pressure The MWP can also be found on the nameplate.
ToF	Time of Flight
DK	Relative dielectric constant $\epsilon_{\rm r}$
Operating tool	The term "operating tool" is used in place of the following operating software: SmartBlue (app), for operation using an Android or iOS smartphone or tablet.
BD	Blocking Distance; no signals are analyzed within the BD.

# 3 Basic safety instructions

### 3.1 Requirements for personnel

The personnel for installation, commissioning, diagnostics and maintenance must fulfill the following requirements:

- Trained, qualified specialists must have a relevant qualification for this specific function and task.
- Are authorized by the plant owner/operator.
- Are familiar with federal/national regulations.
- Before starting work, read and understand the instructions in the manual and supplementary documentation as well as the certificates (depending on the application).
- ► Follow instructions and comply with basic conditions.

The operating personnel must fulfill the following requirements:

- Are instructed and authorized according to the requirements of the task by the facility's owner-operator.
- ► Follow the instructions in this manual.

## 3.2 Designated use

#### Application and media

The measuring device described in these Operating Instructions is intended for continuous, non-contact level measurement in liquids. Because of its operating frequency of approx. 26 GHz, a maximum radiated pulsed power of 5.7 mW and an average power output of 0.015 mW, use outside of closed, metallic vessels is also permitted. For operation outside of closed vessels the device must be installed according to the instructions mentioned in the chapter "Installation"  $\rightarrow \square$  16. Operation does not pose a risk to health or the environment.

If the limit values specified in the "Technical data" and the conditions listed in the instructions and additional documentation are observed, the measuring device may be used for the following measurements only:

- Measured process variables: distance
- Calculated process variables: volume or mass in vessels of any shape; flow through measuring weirs or flumes (calculated from the level by the linearization functionality)

To ensure that the measuring device remains in proper condition for the operation time:

- Use the measuring device only for media against which the process-wetted materials are adequately resistant.
- Observe the limit values in "Technical data".

#### Incorrect use

The manufacturer is not liable for damage caused by improper or non-designated use.

Verification for borderline cases:

 For special fluids and fluids for cleaning, Endress+Hauser is glad to provide assistance in verifying the corrosion resistance of fluid-wetted materials, but does not accept any warranty or liability.

#### Residual risks

Due to heat transfer from the process as well as power dissipation within the electronics, the temperature of the electronics housing and the assemblies contained therein may rise to 80  $^{\circ}$ C (176  $^{\circ}$ F) during operation. When in operation, the sensor can reach a temperature close to the medium temperature.

Danger of burns from contact with surfaces!

► For elevated fluid temperature, ensure protection against contact to prevent burns.

## 3.3 Workplace safety

For work on and with the device:

• Wear the required personal protective equipment according to federal/national regulations.

## 3.4 Operational safety

Risk of injury.

- Operate the device in proper technical condition and fail-safe condition only.
- ► The operator is responsible for interference-free operation of the device.

#### Conversions to the device

Unauthorized modifications to the device are not permitted and can lead to unforeseeable dangers.

▶ If, despite this, modifications are required, consult with the manufacturer.

#### Repair

To ensure continued operational safety and reliability,

- Carry out repairs on the device only if they are expressly permitted.
- Observe federal/national regulations pertaining to repair of an electrical device.
- Use original spare parts and accessories from the manufacturer only.

#### Hazardous area

To eliminate a danger for persons or for the facility when the device is used in the hazardous area (e.g. explosion protection, pressure vessel safety):

- Based on the nameplate, check whether the ordered device is permitted for the intended use in the hazardous area.
- ► Observe the specifications in the separate supplementary documentation that is an integral part of these Instructions.

## 3.5 Product safety

This measuring device is designed in accordance with good engineering practice to meet state-of-the-art safety requirements, has been tested, and left the factory in a condition in which it is safe to operate. It meets general safety standards and legal requirements.

#### 3.5.1 CE mark

The measuring system meets the legal requirements of the applicable EC guidelines. These are listed in the corresponding EC Declaration of Conformity together with the standards applied.

Endress+Hauser confirms successful testing of the device by affixing to it the CE mark.

## 4 Registered trademarks

#### 😵 Bluetooth

The *Bluetooth*<sup>®</sup> word mark and logos are registered trademarks owned by the Bluetooth SIG, Inc. and any use of such marks by Endress+Hauser is under license. Other trademarks and trade names are those of their respective owners."

#### Apple®

Apple, the Apple logo, iPhone, and iPod touch are trademarks of Apple Inc., registered in the U.S. and other countries. App Store is a service mark of Apple Inc.

## Android®

Android, Google Play and the Google Play logo are trademarks of Google Inc.

# 5 Supplementary documentation

The following document types are available in the Download Area of the Endress+Hauser Internet site: www.endress.com  $\rightarrow$  Download:

## 5.1 Standard documentation

Device	Document type	Document code
FMR10	Brief Operating Instructions	KA01247F

Device	Document type	Document code
FMR10	Technical Information	TI01266F

#### **Product description** 6

#### 6.1 Product design

#### 6.1.1 **Micropilot FMR10**



**1** Design of the Micropilot FMR10 (26 GHz)

- 1 Sensor housing
- 2 Seal
- 3 Process connection rear side
- Cable gland Pipe adapter
- 4 5
- 6 . O-ring
- 7 Counter nut
- Design ring 8
- 9 Process connection front side

# 7 Incoming acceptance and product identification

## 7.1 Incoming acceptance



If one of these conditions is not satisfied, contact your Endress+Hauser Sales Center.

## 7.2 Product identification

The following options are available for identification of the measuring device:

- Nameplate specifications
- Extended order code with breakdown of the device features on the delivery note
- Enter serial numbers from nameplates in *W@M Device Viewer* (www.endress.com/deviceviewer): All information about the measuring device and an overview of the scope of the associated Technical Documentation is displayed.
- Enter the serial number from the nameplates into the *Endress+Hauser Operations App*, or scan the 2-D matrix code (QR code) on the nameplate with the *Endress+Hauser Operations App*: All information about the measuring device and an overview of the scope of the associated Technical Documentation is displayed.

2	Endress+Hauser
Order code: 3	Mat.: 17
Ext. ord. cd.:	18
$- \odot$ 6 $\bigcirc$ 7	19
MWP: 8 Ta: 9 T, max: 10	20
DeviceID: 11	
FW: 12 Dev.Rev.: 13 ex works	▲→□ 21
14 15 16	22 x = if modification see sep. label Date: 24

#### ☑ 2 Nameplate of Micropilot

- 1 Manufacturer's address
- 2 Device name
- 3 Order code
- 4 Serial number (ser. no.)
- 5 Extended order code (Ext. ord. cd.)
- 6 Supply voltage
- 7 Signal outputs
- 8 Process pressure
- 9 Permitted ambient temperature  $(T_a)$
- 10 Maximum process temperature
- 11 Device ID
- 12 Firmware version (FW)
- 13 Device revision (Dev.Rev.)
- 14 CE mark
- 15 Additional information about the device version (certificates, approvals)
- 16 C-Tick
- 17 Materials in contact with process
- 18 Degree of protection: e.g. IP, NEMA
- 19 Certificate symbol
- 20 Certificate and approval relevant data
- 21 Document number of the Safety Instructions: e.g. XA, ZD, ZE
- 22 Modification mark
- 23 2-D matrix code (QR code)
- 24 Manufacturing date: year-month

## 8 Installation

### 8.1 Installation conditions

#### 8.1.1 Installation types



■ 3 Wall, ceiling or nozzle installation

- A Wall or ceiling mount, adjustable
- B Mounted at front thread
- C Mounted at rear thread
- D Ceiling installation with counter nut (included in delivery)



#### The sensor cable is not designed as supporting cable. Do not use as a suspension wire.

#### 8.1.2 Nozzle installation

The antenna should be just out of the nozzle for optimum measurement. The interior of the nozzle must be smooth and may not contain any edges or welded joints. The edge of the nozzle should be rounded if possible. The maximum nozzle length  $\mathbf{L}$  depends on the nozzle diameter  $\mathbf{D}$ . Please note the specified limits for the diameter and length of the nozzle.



	40 mm (1.5 in) Antenna, outside nozzle	40 mm (1.5 in) Antenna, inside nozzle
D	min. 40 mm (1.5 in)	min. 80 mm (3 in)
L	max. D x 1.5	max. 140 mm (5.5 in) + D x 1.5



#### 8.1.3 Orientation

■ 5 Tank installation position

- If possible install the sensor so that its lower edge projects into the vessel.
- Do not install the sensor in the middle of the tank (2). We recommend leaving a distance (1) between the sensor and the tank wall measuring 1/6 of the tank diameter.
   Recommended distance A wall nozzle outer edge: ~ 1/6 of the tank diameter D.
   However, the device must not under any circumstances be mounted closer than 15 cm (5.91 in) to the tank wall.
- Avoid measurements through the filling curtain (3).
- Avoid equipment (4) such as limit switches, temperature sensors, baffles, heating coils etc.
- Multiple devices can be operated in one tank without influencing each other.
- No signals are analyzed within the Blocking distance. It can therefore be used to suppress interference signals (e.g. the effects of condensate) close to the antenna. By default an automatic Blocking distance of at least 0.1 m (0.33 ft) is preset. However it can be manually overwritten (even 0 m (0 ft) is allowed. Automatic calculation:

Blocking distance = Empty calibration - Full calibration - 0.2 m (0.656 ft). The **Blocking distance** parameter is recalculated according to this formula every time a new value is entered into the **Empty calibration** parameter or **Full calibration** parameter.

If this calculation results in a value <0.1 m (0.33 ft), the blocking distance of 0.1 m (0.33 ft) is used instead.

#### 8.1.4 Alignment

- Align the antenna vertically to the product surface.
- Align the eyelet with the mounting eye as well as possible towards the tank wall.



*■* 6 Sensor alignment when mounting in tank

#### 8.1.5 Beam angle



☑ 7 Relationship between beam angle a, distance D and beamwidth diameter W

The beam angle is defined as the angle  $\alpha$  at which the power density of the radar waves reaches half the value of the maximum power density (3dB width). Microwaves are also emitted outside the signal beam and can be reflected off interfering installations.

Beam diameter W as a function of beam angle  $\alpha$  and measuring distance D.

FMR10	
Antenna size40 mm (1.5 in)	
Beam angle α	30°
Distance (D)	Beamwidth diameter W
3 m (9.8 ft)	1.61 m (5.28 ft)
5 m (16.4 ft)	2.68 m (8.79 ft)

#### 8.1.6 Measurement in plastic vessels

If the outer wall of the vessel is made of a non-conductive material (e.g. GFR) microwaves can also be reflected off interfering installations outside of the vessel (e.g. metallic pipes (1), ladders (2), grates (3), ...). Therefore there should be no such interfering installations in the signal beam. For more information, please contact Endress+Hauser.



8 Measurement in a plastic vessel

#### 8.1.7 Weather protection cover

For outdoor use, the use of a weather protection cover(1) is recommended



☑ 9 Weather protection cover, e.g with 40 mm (1.5") antenna

The sensor is not completely covered.

1

The weather protection cover is available as an accessory.  $\rightarrow \implies 34$ 

#### 8.1.8 Free-field measurement with flooding protection tube

The flooding protection tube guarantees a definitive analysis of the maximum level even in the event that the sensor is completely flooded.

In free-field installations and / or in applications where there is a risk of flooding, it is recommended to use a flooding protection tube



ID Function of flooding protection tube

- 1 Air pocket
- 2 O-ring (EPDM) seal
- 3 Blocking distance
- 4 Max. Level

The flooding protection tube is available as an accessory.  $\rightarrow \square 34$ 

The tube is screwed directly onto the sensor and seals off the system by means of an Oring (2) making it air-tight. In the event of flooding, the air pocket (1) that develops in the tube ensures a definitive detection of the maximum level (4) directly at the end of the tube. Due to the fact that the Blocking distance (3) is inside the tube, multiple echoes are not analyzed.

#### Configuring the blocking distance when using the flooding protection tube

Navigate to: Main menu → Setup → Advanced setup → Blocking distance
 Enter 100 mm (4 in).

#### 8.1.9 Installation with mounting bracket, adjustable



Installation with mounting bracket, adjustable

- Wall or ceiling installation is possible.
- Using the mounting bracket, position the antenna so that it is perpendicular to the product surface.

#### NOTICE

# There is no conductive connection between the mounting bracket and transmitter housing.

Risk of electrostatic charge.

• Integrate the mounting bracket in the local potential equalization system.

🖪 The mounting bracket is available as an accessory. → 🗎 34

#### 8.1.10 Cantilever installation, with pivot



12 Cantilever installation, with pivot

- A Installation with cantilever and wall bracket
- *B* Installation with cantilever and mounting frame
- *C* The cantilever can be turned (e.g. in order to position the sensor over the center of the channel, for example)

#### 8.1.11 Post-installation check

Is the device undamaged (visual inspection)?
Is the device adequately protected from wet conditions and direct sunlight?
Is the device properly secured?

# 9 Electrical connection

### 9.1 Cable assignment



🖻 13 Cable assignment

- 1 Plus, brown wire
- 2 Minus, blue wire

## 9.2 Supply voltage

An external power supply is necessary.

Terminal voltage U at device	Maximum load R, depending on supply voltage $\mathbf{U}_0$ of power supply unit			
10.5 to 30 V <sub>DC</sub> 2-wire	R [Ω] 500 0 10 10 10.5 20 30 U <sub>0</sub> [V] 40029226			

#### Potential equalization

No special measures for potential equalization are required.



Various power supply units can be ordered from Endress+Hauser.

#### 📔 Battery operation

The sensor's  $Bluetooth^{(\!\!\!\!\ R)}$  wireless technology communication can be disabled to increase the operating life of the battery.

→ 🖺 29

# 9.3 Connection 4 to 20 mA



## 9.4 Post-connection check

Is the device or cable undamaged (visual check)?
Do the cables have adequate strain relief?
Are the cable glands mounted and firmly tightened?
Does the supply voltage match the specifications on the nameplate?
No reverse polarity, is terminal assignment correct?

# 10 Operability

## **10.1** Operating concept

- 4 to 20 mA
- SmartBlue (app) via *Bluetooth*® wireless technology
- Menu guidance with brief explanations of the individual parameter functions in the operating tool

# 10.2 Via Bluetooth<sup>®</sup> wireless technology



■ 15 Possibilities for remote operation via Bluetooth<sup>®</sup> wireless technology

- 1 Transmitter power supply unit
- 2 Smartphone / tablet with SmartBlue (app)
- 3 Transmitter with Bluetooth® wireless technology

# 11 Commissioning and operation

## 11.1 Installation and function check

Make sure that all final checks have been completed before you start up your measuring point.

## **11.2** Operation and settings via SmartBlue (app)

SmartBlue is available as download for Android devices from the Google Play Store and for iOS devices from the iTunes Store.

If you scan the QR code, you will be brought directly to the app:





#### System requirements

- iOS devices: iPhone 4S or higher from iOS9.0; iPad2 or higher from iOS9.0; iPod Touch 5. Generation or higher from iOS9.0
- Android devices: from Android 4.4 KitKat and Bluetooth® 4.0

1. Download and install SmartBlue

2. Start SmartBlue

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7. Change the password after logging in for the first time



8. You can drag additional information (e.g. main menu) onto the screen by swiping across the screen.



🖻 19 🛛 Main menu

Envelope curves can be displayed and recorded

#### Additionally to the envelope curve, the following values are displayed:

- D = Distance
- L = Level
- A = Absolute amplitude
- At screenshots, the displayed section (zoom function) is saved
- In video sequences, always the whole area without zoom function is saved

It is also possible to send envelope curves (video sequences) using the relevant smartphone or tablet functions



🖻 20 Android view

- 1 Record video
- 2 Create screenshot
- 3 Start / stop video recording
- 4 Send video 5 Navigate to
- 5 Navigate to mapping menu
- 6 Move time on time axis

Endress+Hauser



21 iOS view

- 1 Record video
- 2 Create screenshot
- 3 Send video
- Navigate to mapping menu Start / stop video recording Move time on time axis 4 5
- 6

# 11.3 Configuring level measurement via operating software



- 22 Configuration parameters for level measurement in liquids
- R Reference point of measurement
- D Distance
- L Level
- E Empty calibration (= zero point)
- *F* Full calibration (= span)
- BD Blocking distance
- 1. Navigate to: Setup  $\rightarrow$  Device tag
- 2. Navigate to: Setup  $\rightarrow$  Distance unit
  - $\blacktriangleright$  Select unit of length for distance calculation
- 3. Navigate to: Setup  $\rightarrow$  Empty calibration
  - └ Specify empty distance E (distance from reference point R to minimum level)
- 4. Navigate to: Setup  $\rightarrow$  Full calibration
  - └ Specify full distance F (span: max. level min. level)
- 5. Navigate to: Setup  $\rightarrow$  Distance
  - Shows the distance D that is currently measured from the reference point (lower edge of flange / last thread of the sensor) to the level
- 6. Navigate to: Setup  $\rightarrow$  Level
  - └ Shows the level L measured
- 7. Navigate to: Setup  $\rightarrow$  Signal quality
  - └ → Displays the signal quality of the analyzed level echo
- 8. Navigate to: Setup  $\rightarrow$  Confirm distance
  - └ Compare the distance displayed with the actual value to start recording an interference echo map
- 9. Navigate to: Setup  $\rightarrow$  Mapping end point
  - └ This parameter determines the distance up to which the new mapping is to be recorded
- 10. Navigate to: Setup  $\rightarrow$  Present mapping
  - └ Displays the distance up to which a mapping has already been recorded

#### 11.3.1 Displaying level value as %

In combination Full calibration with Empty calibration and given 4 to 20 mA output signal, the level value for 4 mA (=Empty) and the level value for 20 mA (=Full) can be determined directly in the unit of length used.

The Full calibration can be used to calculate a standardized signal proportionate to the level e.g. 0 to 100 % level. The two basic values of 0 % and 100 % can in turn be assigned directly to the analog output values 4 mA and 20 mA.

Х	Level in m	Y	Output signal as %
X1	0.00 m (0.00 ft)	Y1	0 %
X2	Value F (=Full)	Y2	100 %

#### Configuration using SmartBlue

- 1. Navigate to: Main menu  $\rightarrow$  Setup  $\rightarrow$  Advanced setup  $\rightarrow$  Linearization type
  - └ Select table as the linearization type
- 2. Select linearization table
- 3. X1 = Specify level value in m / ft for 0 %
- 4. X2 = Specify level value in m / ft for 100 %
- 5. Activate linearization table

## 11.4 Data access - Security

#### 11.4.1 Software locking via access code in SmartBlue

The configuration data can be write-protected using an access code (software locking).

Navigate to: Setup → Advanced setup → Administration → Administration1 → Define access code → Confirm access code

The entered code must be different from "0000" and the last release code.

Once the access code has been defined, write-protected devices can be switched to maintenance mode only if the access code is entered in the **Enter access code** parameter. If the factory setting is not changed or if 0000 is entered, the device is in maintenance mode and its configuration data are therefore **not** write-protected and can be changed at any time.

#### 11.4.2 Unlocking via SmartBlue

Navigate to: Setup → Advanced setup → Zugriffsrechte Bediensoftware → Enter access code

#### 11.4.3 Bluetooth® wireless technology

Signal transmission via Bluetooth<sup>®</sup> wireless technology is done by an ecryption method tested by the Fraunhofer-Institut (Third Party).

- Without the SmartBlue App, the device is not visible via *Bluetooth*® wireless technology
- Only one point-to-point connection between **one** sensor and **one** smartphone or tablet is established.
- The *Bluetooth®* wireless technology interface can be deactivated in SmartBlue

#### Deactivate Bluetooth® wireless technology interface

Navigate to: Setup → Communication → Bluetooth configuration → Bluetooth mode
 Switch off *Bluetooth*<sup>®</sup> wireless technology interface. "Off" position disables remote access via app

#### Re-activate Bluetooth® wireless technology interface

If *Bluetooth*<sup>®</sup> wireless technology interface was disabled, it can be re-activated only after performing the following recovery sequence:

- 1. Connect device to voltage supply
  - └ ► After a waiting time of 10 minutes, a time window of 2 minutes opens
- 2. During this time window it is possible to re-activate the FMR10 *Bluetooth*<sup>®</sup> wireless technology interface using SmartBlue (app)
- 3. Navigate to: Setup  $\rightarrow$  Communication  $\rightarrow$  Bluetooth configuration  $\rightarrow$  Bluetooth mode
  - └ Switch on *Bluetooth*<sup>®</sup> wireless technology interface. "On" position enables remote access via app



☑ 23 Timeline for Bluetooth<sup>®</sup> wireless technology recovery sequence , time in minutes

# 12 Diagnostics and troubleshooting

# 12.1 General trouble shooting

## 12.2 General errors

Error	Possible cause	Remedy
Device is not responding.	Supply voltage does not match the value indicated on the nameplate	Apply correct voltage
	The polarity of the supply voltage is wrong	Correct the polarity
	Connecting cables are not in contact with the terminals	Check the connection of the cables and correct if necessary
Device measures incorrectly	Configuration error	<ul><li>Check and correct the parameter configuration</li><li>Perform mapping</li></ul>
Linearized output value not plausible	Linearization error	SmartBlue : Check linearization table
Device not accessible via SmartBlue	No Bluetooth connection	Enable Bluetooth function on smartphone or tablet
		Bluetooth function of sensor disabled, perform recovery sequence
		Device already linked to another smartphone / tablet
Login via SmartBlue not possible	Device is being put into operation for the first time	Enter initial password (device serial number) and change.
Device cannot be operated via	Incorrect password entered	Enter correct password
SmartBlue	Password forgotten	Contact Endress+Hauser Service

## 12.3 Diagnostic event

#### 12.3.1 Diagnostic event in the operating tool

If a diagnostic event is present in the device, the status signal appears in the top left status in the operating tool along with the corresponding symbol for event level in accordance with NAMUR NE 107:

- Failure (F)
- Function check (C)
- Out of specification (S)
- Maintenance required (M)

#### Calling up remedy information

1. Navigate to the **Diagnostics** menu.

- └ In the Actual diagnostics parameter, the diagnostic event is shown with event text
- 2. On the right in the display range, hover the cursor over the **Actual diagnostics** parameter.
  - ← A tool tip with remedy information for the diagnostic event appears

## 12.4 List of diagnostic events

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]			
Diagnostic of electronic							
270	Main electronic failure	Exchange device	F	Alarm			
271	Main electronic failure	<ol> <li>Restart device</li> <li>If failure remains, exchange device.</li> </ol>	F	Alarm			
272	Main electronic failure	<ol> <li>Restart device</li> <li>Check enviroment for strong EMC fields</li> <li>If failure remains, exchange device.</li> </ol>	F	Alarm			
283	Memory content	<ol> <li>Transfer data or reset device</li> <li>Contact service</li> </ol>	F	Alarm			
Diagnostic of co	nfiguration						
410	Data transfer	<ol> <li>Check connection</li> <li>Retry data transfer</li> </ol>	F	Alarm			
411	Up-/download active	Up-/download active, please wait	С	Warning			
435	Linearization	Check linearization table	F	Alarm			
438	Dataset	<ol> <li>Check data set file</li> <li>Check device configuration</li> <li>Up- and download new configuration</li> </ol>	М	Warning			
441	Current output 1	<ol> <li>Check process</li> <li>Check current output settings</li> </ol>	S	Warning			
491	Current output 1 simulation	Deactivate simulation	С	Warning			
585	Simulation distance	Deactivate simulation	С	Warning			

Diagnostic number	Short text	Remedy instructions	Status signal [from the factory]	Diagnostic behavior [from the factory]			
586	Record map	Recording of mapping please wait	С	Warning			
Diagnostic of pr	Diagnostic of process						
801	Energy too low	Increase supply voltage	S	Warning			
825	Operating temperature	<ol> <li>Check ambient temperature</li> <li>Check process temperature</li> </ol>	S	Warning			
941	Echo lost	Check parameter 'Evaluation	S	Warning			
941	Echo lost	sensitivity	F	Alarm			

# 13 Maintenance

No special maintenance work is required.

## 13.1 Exterior cleaning

When cleaning the exterior, always use cleaning agents that do not attack the device surfaces or the seals.

## 13.2 Seals

The process seals of the sensor (at the process connection) should be replaced periodically. The interval between changes depends on the frequency of the cleaning cycles, the cleaning temperature and the medium temperature.

# 14 Repair

## 14.1 General notes

#### 14.1.1 Repair concept

The Endress+Hauser repair concept is devised in such a way that repairs can only be carried out through device replacement.

#### 14.1.2 Replacing a device

Once the device has been replaced, parameters must be reconfigured and interference echo suppression or linearization may need to be carried out once again.

#### 14.1.3 Return

The measuring device must be returned if the wrong device has been ordered or delivered. As an ISO-certified company and also due to legal regulations, Endress+Hauser is obliged to follow certain procedures when handling any returned products that have been in contact with medium. To ensure safe, swift and professional device returns, please refer to the procedure and conditions for returning devices provided on the Endress+Hauser website at http://www.endress.com/support/return-material

#### 14.1.4 Disposal

When disposing, separate and recycle the device components based on the materials.

# 15 Accessories

## 15.1 Overview

Device-specific accessories

Accessories	Description	Order number
Weather protection cover	Material: PVDF	52025686
	The sensor is not completely covered.	
Securing nut G1-1/2	Suitable for use with devices with G 1-1/2 and MNPT 1-1/2 process connection. Material: PC	52014146
Flooding protection tube	Material: metallized PBT-PC	71325090
Mounting bracket, adjustable	Consists of: Mounting bracket: 316L (1.4404) Angle bracket: 316L (1.4404) Screws: A4 Retaining rings: A4	71325079

#### Device-specific accessories - flanges

Accessories Description		Order number		
Flanges	Material: miscellaneous	For details, see Technical Information TI00426F		

#### System components

Accessories	Description	Reference
RMA42	Digital process transmitter for monitoring and visualizing analog measured values	For details, see Technical Information TI00150R and Operating Instructions BA00287R
RIA452	Digital process meter RIA452 in panel mounted housing for monitoring and displaying analog measured values with pump control and batch functions and flow calculation	For details, see Technical Information TI113R and Operating Instructions BA00254R
HAW562	Surge arrester for DIN rail according to IEC 60715, used to protect electronic components from being destroyed by overvoltage	For details, see Technical Information TI01012K

For additional suitable accessories, see Technical Information TI01267F (FMR20)

# 16 Operating menu

# 16.1 Overview operating menue (SmartBlue)

	Nav	vigation	🗐 🗐 Operating	menu	
Main menu		]			
	► Setup		]		→ 🗎 39
		► Basic setup	-	]	
			Devrice tog		그 🖻 20
					/ = )}
			Distance unit		→ 🗎 39
			Empty calibration		→ 🗎 39
			Full calibration		→ 🗎 39
			Distance		→ 🗎 40
			Level		→ 🗎 40
			Signal quality		→ 🗎 40
		► Mapping		]	
			Confirm distance		→ 🗎 41
			Mapping end point		→ 🖺 41
			Present mapping		→ 🖺 41
		► Advanced setup		]	→ 🗎 42
			► Access status to	oling	
				Access status tooling	] → 🖺 42
				Enter access code	] → 🖺 42
			► Advanced settin	gs	
				Evaluation sensitivity	] → 🗎 42
				Changing velocity	→ 🖺 43

	First Echo sensitivity	→ 🗎 43
	Output mode	→ 🖺 43
	Blocking distance	→ 🖺 44
	Level correction	→ 🗎 44
	Evaluation distance	→ 🗎 44
► Safety settings		→ 🗎 46
	Delay time echo lost	→ 🗎 46
	Diagnostics echo lost	→ 🗎 46
► Current output		→ 🗎 47
	Output current	→ 🗎 47
	Damping output	→ 🗎 47
	Turn down	→ 🗎 47
	4 mA value	→ 🖺 48
	20 mA value	→ 🗎 48
	Trim	→ 🗎 48
	Trim value high	→ 🗎 49
	Trim value low	→ 🗎 49
► Administration		→ 🖺 50
	► Administration 1	
	Define access code	→ 🖺 50
	Confirm access code	→ 🗎 50
	Device reset	→ 🗎 50
	► Administration 2	
	Free field special	→ 🖺 51

	► Linearization ta	ble			
		Distance unit			→ 🗎 39
		Linearization type			→ 🗎 45
		Level linearized			→ 🗎 45
	► Communication				→ 🗎 52
		► Bluetooth config	uration		→ 🗎 52
			Bluetooth mode		→ 🗎 52
► Diagnostics		]			→ 🗎 53
	► Diagnostics				→ 🗎 53
		Actual diagnostics			→ 🗎 53
		Previous diagnostics			→ 🗎 53
		Delete previous diag	nostic		→ 🗎 53
		Signal quality			→ 🗎 40
	► Device informat	ion			→ 🗎 55
		Device name			→ 🗎 55
		Firmware version			→ 🗎 55
		Extended order code	1		→ 🗎 55
		Extended order code	2		→ 🗎 55
		Extended order code	3	]	→ 🗎 55
		Order code			→ 🗎 56
		Serial number			→ 🗎 56
		ENP version			→ 🗎 56
	► Simulation				→ 🗎 57
		Simulation			→ 🗎 57

Value current output 1	] → 🗎 57
Process variable value	) → 🗎 57

Â

# 16.2 "Setup" menu

Indicates how to navigate to the parameter using operating tools
 Indicates parameters that can be locked via the access code.

Navigation 🛛 Setup

Device tag		
Navigation		
Description	Enter a unique name for the measuring point to identify the device quickly within the plant.	
Factory setting	EH_FMR10_####### (last 7 digits of the device serial number)	

Distance unit

Navigation		
Description	Used for the basic calibration	n (Empty / Full).
Selection	<i>SI units</i> m	<i>US units</i> ft
Factory setting	m	

□ Setup → Empty calibr.	
Distance between process connection and minimum level (0%).	
0.0 to 5 m	
5 m	
	<ul> <li>□ Setup → Empty calibr.</li> <li>Distance between process connection and minimum level (0%).</li> <li>0.0 to 5 m</li> <li>5 m</li> </ul>

Navigation		Setup $\rightarrow$ Full calibr.
Description	Distar	nce between minimum level (0%) and maximum level (100%).

User entry	0.0 to 5 m
Factory setting	4.8 m
Distance	
Navigation	$\Box \qquad \text{Setup} \rightarrow \text{Distance}$
Description	Displays the current measured distance D from the reference point (lower edge of the flange / last thread of the sensor) to the level.
User interface	0.0 to 5 m
Level	
Navigation	$\Box  \text{Setup} \rightarrow \text{Level}$
Description	Displays the measured level L (before linearization). The unit is defined in the 'Distance unit' parameter (factory setting = m).
User interface	-99999.9 to 200000.0 m
Factory setting	0.0 m
Signal quality	
Navigation	□ Setup $\rightarrow$ Signal quality
Description	Displays the signal quality of the level echo. Meaning of the display options - Strong: The evaluated echo exceeds the threshold by at least 10 dB Medium: The evaluated echo exceeds the threshold by at least 5 dB Weak: The evaluated echo exceeds the threshold by less than 5 dB No signal: The device does not find an usable echo. The signal quality indicated in this parameter always refers to the currently evaluated echo, either the level echo or the tank bottom echo. In case of a lost echo ('Signal quality' = No signal) the device generates the following error message: 'Diagnostic echo lost' = Warning (factory setting) or Alarm, if the other option has been selected in 'Diagnostic echo lost'.
User interface	<ul> <li>Strong</li> <li>Medium</li> <li>Weak</li> <li>No signal</li> </ul>

Confirm distance	
Navigation	□ Setup $\rightarrow$ Confirm distance
Description	Does the measured distance match the real distance? Select one of the options: - Manual map To be selected if the range of mapping is to be defined manually in the 'Mapping end point' parameter. A comparison between actual and indicated distance is not required in this case Distance ok To be selected if the measured distance matches the actual distance. The device performs a mapping Distance unknown To be selected if the actual distance is unknown. A mapping can not be performed in this case Factory map To be selected if the present mapping curve (if one exists) is to be deleted. The device returns to the 'Confirm distance' parameter and a new mapping can be recorded.
Selection	<ul> <li>Manual map</li> <li>Distance ok</li> <li>Distance unknown</li> <li>Factory map</li> </ul>
Factory setting	Distance unknown

Mapping end point		A
Navigation	Setup $\rightarrow$ Map. end point	
Description	This parameter defines up to which distance the new mapping is to be recorded. The distance is measured from the reference point, i.e. from the lower edge of the mounting flange or sensor.	
User entry	0 to 20 m	
Factory setting	0 m	
Present mapping		

Navigation	$ \qquad \qquad$
Description	Indicates up to which distance a mapping has already been recorded.
User interface	0 to 100 m

## 16.2.1 "Advanced setup" submenu

Navigation

Access status tooling	
Navigation	$ \qquad \qquad$
Description	Shows the access authorization to the parameters via the operating tool.
User interface	<ul> <li>Operator</li> <li>Maintenance</li> <li>Service</li> <li>Production</li> <li>Development</li> </ul>
Factory setting	Maintenance

Enter access code	
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Ent. access code
Description	To change from operator to maintenance, the customer-specific access code, which has been defined in the <b>Define access code</b> parameter has to be entered. If an incorrect access code is entered, the device remains in the Operator Mode. Please contact your Endress+Hauser Sales Center if you lose your access code.
User entry	0 to 9 999
Factory setting	0
Evaluation sensitivity	٨
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Evaluation sens.
Description	Selection of the evaluation sensitivity Options to select from: - Low The weighting curve is high for low evaluation sensitivity. Interferers but also small level signals are not recognized Medium The weighting curve is in a medium region High The weighting curve is low for high evaluation sensitivity. Interferers but also small level signals can be reliably detected.
Selection	<ul><li>Low</li><li>Medium</li><li>High</li></ul>
Factory setting	Medium

Changing velocity		Â
Navigation	$ \qquad \qquad$	
Description	Selection of the expected draining or filling speed of the measured level.	
Selection	<ul> <li>Slow &lt;10 cm (0,4 in)/min</li> <li>Standard &lt;1 m (40 in)/min</li> <li>Fast &gt;1 m (40 in)/min</li> <li>No filter / test</li> </ul>	
Factory setting	Standard <1 m (40 in)/min	
First Echo sensitivity		Â
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ First Echo sens.	
Description	This parameter describes the band for First Echo evaluation. Is measured / calculated down from the peak of the current level echo. Options to select from: - Low The band f the first echo evaluation is very narrow. The evaluation stays longer at the found echo respectively does not jump to the next Echo or distortion signal Medium The band for the first echo evaluation has an average width High The band for the first echo or distortion signal.	or or
Selection	<ul><li>Low</li><li>Medium</li><li>High</li></ul>	
Factory setting	Medium	
Output mode		
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Output mode	

DescriptionSelect output mode between: Ullage = The remaining space in the tank or silo is indicated.<br/>or Level linearized = The level is indicated (more precisely: the linearized value if a<br/>linearization has been activated).

- Selection Ullage • Level linearized
- Factory setting Level linearized

Blocking distance		ß
Navigation	$ \qquad \qquad$	
Description	Specify blocking distance (BD). No signals are evaluated within the blocking distance. Therefore, BD can be used to suppress interference signals in the vicinity of the antenna Note: The measuring range should not overlap with the blocking distance.	
User entry	0.0 to 5 m	
Factory setting	By default an automatic Blocking distance of at least 0.1 m (0.33 ft) is preset. However is can be manually overwritten (even 0 m (0 ft) is allowed. Automatic calculation of the Blocking distance = Empty calibration - Full calibration - 0.2 m (0.656 ft). The <b>Blocking distance</b> parameter is recalculated according to this formula every time a new value is entered into the <b>Empty calibration</b> parameter or <b>Full calibration</b> parameter If this calculation results in a value <0.1 m (0.33 ft), the blocking distance of 0.1 m (0.33 ft) is used instead.	t er.

Level correction	
Navigation	$ \qquad \qquad$
Description	The measured level is corrected by this value to compensate for a constant level error. Level correction > 0: The level is increased by this value. Level correction < 0: The level is decreased by this value.
User entry	-25 to 25 m
Factory setting	0.0 m

Evaluation distance		
Navigation	$ \qquad \qquad$	
Description	Extended signal search area. Is generally greater than the empty distance. If the signal found below the empty distance, '0' (empty) is indicated as measured value. Only for signals, detected below the 'Evaluation distance', the error 'Echo Lost' is issued. e.g. flow measurement in overflow weirs.	al is w
User entry	0 to 20 m	
Factory setting	7.5 m	

Linearization type		
Navigation	$ \qquad \qquad$	
Description	<ul> <li>Linearization types</li> <li>Meaning of the options:</li> <li>None: The level is transmitted in the level unit without linearization.</li> <li>Table: The relationship between the measured level L and the output value(volume/flow/weight) is given by a linearization table consisting of up to 32 pairs of values "level - volume" or "level - flow"or "level - weight", respectively.</li> <li>Remark: To create / modify a linearization table please open the linearization module in SmartBlue.</li> </ul>	
Selection	<ul><li>None</li><li>Table</li></ul>	
Factory setting	None	
Level linearized		

Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Level linearized
Description	Currently measured level.
User interface	Signed floating-point number

#### "Safety settings" submenu

Navigation

 $\blacksquare \square \quad \text{Setup} \rightarrow \text{Advanced setup} \rightarrow \text{Safety sett.}$ 

Delay time echo lost	ß
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Safety sett. $\rightarrow$ Delay echo lost
Description	Define the delay time in the case of an echo loss. After an echo loss, the device waits for the time specified in this parameter before reacting as specified in the Diagnostic echo lost parameter. This helps to avoid interruptions of the measurement by short-term interferences.
User entry	0 to 600 s
Factory setting	300 s
Diagnostics echo lost	8
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Safety sett. $\rightarrow$ Diagn. echo lost
Description	At this parameter it can be set if in case of a lost echo a warning or an alarm is issued.
Selection	<ul><li>Warning</li><li>Alarm</li></ul>
Factory setting	Warning

#### "Current output" submenu

*Navigation*  $\square$  Setup  $\rightarrow$  Advanced setup  $\rightarrow$  Curr.output

Output current	
Navigation	Setup $\rightarrow$ Advanced setup $\rightarrow$ Curr.output $\rightarrow$ Output curr.
Description	Shows the actual calculated value of the output current.
User interface	3.59 to 22.5 mA
Damping output	 
Navigation	$ \qquad \qquad$
Description	Define time constant $\tau$ for the damping of the output current. Fluctuations of the measured value affect the output current with an exponential delay, the time constant $\tau$ of which is defined in this parameter. With a small time constant the output reacts immediately to changes of the measured value. With a big time constant the reaction of the output is more delayed. For $\tau = 0$ there is no damping.
User entry	0.0 to 300 s
Factory setting	1.0 s
Turn down	 
Navigation	$ \qquad \qquad$
Description	Using the turn down functionality it is possible to map a section of the measuring range to the total range of the output current (4-20mA). The section is defined by the '4 mA value' and '20 mA value' parameters. Without the turn down, the complete measuring range (0 to 100%) is mapped to the current output (4 to 20mA).
Selection	<ul><li>Off</li><li>On</li></ul>
Factory setting	Off

4 mA value	۵
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Curr.output $\rightarrow$ 4 mA value
Description	Value for 4-mA at Turn down parameter' = On Using the turn down functionality it is possible to map a section of the measuring range to the total range of the output current (4-20mA). The section is defined by the '4 mA value' and '20 mA value' parameters. Without the turn down, the complete measuring range (0 to 100%) is mapped to the current output (4 to 20mA). Note: If '20 mA value' is smaller than '4 mA value', the current output is inverted, which means that an increase of the process variable results in a decrease of the output current.
User entry	Signed floating-point number
Factory setting	0 m
20 mA value	8
Navigation	$ \qquad \qquad$
Description	Value for 20-mA at Turn down' parameter = On Using the turn down functionality it is possible to map a section of the measuring range to the total range of the output current (4-20mA). The section is defined by the '4 mA value' and '20 mA value' parameters. Without the turn down, the complete measuring range (0 to 100%) is mapped to the current output (4 to 20mA). Note: If '20 mA value' is smaller than '4 mA value', the current output is inverted, which means that an increase of the process variable results in a decrease of the output current.
User entry	Signed floating-point number
Factory setting	5 m
Trim	
Navigation	$ \qquad \qquad$
Description	Select action for the recalibration of the current output. The trim can be used to compensate a drift of the current output (which might be caused by very long cables or by a connected Ex barrier, for example). Steps of the trim: 1. Select 'Trim' = 4 mA, 2. Measure

the output current with a gauged multimeter. If it is not equal to 4 mA: Enter measured value in the 'Trim value low' parameter. 3. Select Trim' = 20 mA. 4. Measure the output current with a gauged multimeter. If it is not equal to 20 mA: Enter the measured current into the 'Trim value high' parameter. 5. Select 'Trim' = Calculate. The device calculates the

new scaling of the output current and stores it in the RAM.

Selection	<ul> <li>Off</li> <li>4 mA</li> <li>20 mA</li> <li>Calculate</li> <li>Reset</li> </ul>	
Factory setting	Off	
Trim value high		Ê
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Curr.output $\rightarrow$ Trim value high	
Description	Enter upper measured value for the trim (around 20 mA). After this value has been entered: Select 'Trim' = Calculate. This initiates the recalibration of the current output.	
User entry	18.0 to 22.0 mA	
Factory setting	20.0 mA	

Trim value low	ඕ
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Curr.output $\rightarrow$ Trim value low
Description	Enter lower measured value for the trim (around 4 mA). After this value has been entered: Select 'Trim' = Calculate. This initiates the recalibration of the current output.
User entry	3.0 to 5.0 mA
Factory setting	4.0 mA

#### "Administration" submenu

*Navigation*  $\blacksquare \blacksquare$  Setup  $\rightarrow$  Ad

 $\blacksquare \blacksquare \quad \text{Setup} \rightarrow \text{Advanced setup} \rightarrow \text{Administration}$ 

Define access code		£
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Administration $\rightarrow$ Def. access code	
Description	Define release code for changing device operation mode. If the factory setting is not changed or 0000 is defined as the access code, the device works in maintenance mode without write-protection and the configuration data of the device can then always be modified. Once the access code has been defined, write-protected devices can only be changed to maintenance mode if the access code is entered in the 'Enter access code' parameter. The new access code is only valid after it has been confirmed in the 'Confirm access code' parameter. Please contact your Endress+Hauser Sales Center if you lose you access code.	r
User entry	0 to 9 999	
Factory setting	0	
Confirm access code		ß
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Administration $\rightarrow$ Confirm code	
Description	Re-enter the entered access code to confirm.	
User entry	0 to 9 999	
Factory setting	0	
Device reset		A

Navigation	$ \qquad \qquad$
Description	Reset the device configuration - either entirely or in part - to a defined state.
Selection	<ul><li>Cancel</li><li>To factory defaults</li></ul>
Factory setting	Cancel

Free field special		Ê
Navigation	□ Setup $\rightarrow$ Advanced setup $\rightarrow$ Administration $\rightarrow$ Free field spec.	
Description	Switch the free field option on or off. This parameter can be switched on for free field applications (e.g. below bridges). Caution: The customer map (if one exists) is reset to factory map!.	the
Selection	<ul><li>Off</li><li>On</li></ul>	
Factory setting	Off	

	16.2.2 "Communic	ation" submenu
	Navigation 🛛 🗐 🗎	Setup $\rightarrow$ Communication
	"Bluetooth configuration	" submenu
	Navigation 🛛 🗐 🗎	Setup $\rightarrow$ Communication $\rightarrow$ Bluetooth conf.
Divete eth mode		രി
Navigation	Setup → Communic	ation $\rightarrow$ Bluetooth conf. $\rightarrow$ Bluetooth mode
Description	Enable or disable Bluetoot remote access via the app via the app: Please follow	h function Remark: Switching to position 'Off' will disable with immediate effect. To re-establish a Bluetooth connection the advices in the manual.
Selection	<ul><li>Off</li><li>On</li></ul>	
Factory setting	On	

# 16.3 "Diagnostics" submenu

Navigation

■ □ Diagnostics

Actual diagnostics		
Navigation	□ Diagnostics $\rightarrow$ Actual diagnos.	
Description	Displays current diagnostic message. If several messages are active at the same time, the messages with the highest priority is displayed.	
Previous diagnostics		
Navigation	□ Diagnostics $\rightarrow$ Prev.diagnostics	

Description	Displays the last diagnostic message, with its diagnostic information, which has been
	active before the current message. The condition displayed may still apply.

Delete previous diagnostic		A
Navigation	□ Diagnostics $\rightarrow$ Del. prev. diag.	
Description	Delete previous diagnostic message? It is possible that the diagnostic message remains valid.	
Selection	<ul><li>No</li><li>Yes</li></ul>	
Factory setting	No	
Signal quality		
Navigation	□ Diagnostics $\rightarrow$ Signal quality	
Description	Displays the signal quality of the level echo. Meaning of the display options - Strong: The evaluated echo exceeds the threshold by at least 10 dB Medium: The evaluated echo exceeds the threshold by at least 5 dB Weak: The evaluated echo exceeds the threshol by less than 5 dB No signal: The device does not find an usable echo. The signal quality indicated in this parameter always refers to the currently evaluated echo, either the level echo or the tank bottom echo. In case of a lost echo ('Signal quality' = No signal) the devi generates the following error message: 'Diagnostic echo lost' = Warning (factory setting) Alarm, if the other option has been selected in 'Diagnostic echo lost'.	e d l ce or

#### User interface

- StrongMedium
- Weak
- No signal

### 16.3.1 "Device information" submenu

*Navigation*  $\square$  Diagnostics  $\rightarrow$  Device info

Device name			
Navigation		Diagnostics $\rightarrow$ Device info $\rightarrow$ Device name	
Description	Show	ws the name of the transmitter	
Description	51101		
Factory setting	Micr	ropilot FMR10	
Firmware version			
Navigation		Diagnostics $\rightarrow$ Device info $\rightarrow$ Firmware version	
Description	Show	vs the device firmware version installed.	
Extended order code 1			
Navigation		Diagnostics $\rightarrow$ Device info $\rightarrow$ Ext. order cd. 1	
Description	Shows the 1st part of the extended order code.		
Extended order code 2			
Navigation		Diagnostics $\rightarrow$ Device info $\rightarrow$ Ext. order cd. 2	
Description	Shov	Shows the 2nd part of the extended order code.	
Extended order code 3			
Navigation		Diagnostics $\rightarrow$ Device info $\rightarrow$ Ext. order cd. 3	
Description	Show	vs the 3rd part of the extended order code.	

□ Diagnostics $\rightarrow$ Device info $\rightarrow$ Order code
Shows the device order code.
□ Diagnostics $\rightarrow$ Device info $\rightarrow$ Serial number
Shows the serial number of the measuring device.
□ Diagnostics $\rightarrow$ Device info $\rightarrow$ ENP version
Shows the version of the electronic nameplate (ENP).

#### 16.3.2 "Simulation" submenu

*Navigation*  $\square$  Diagnostics  $\rightarrow$  Simulation

Simulation		£
Navigation	□ Diagnostics $\rightarrow$ Simulation $\rightarrow$ Simulation	
Description	Select process variable to be simulated. The Simulation is used to simulate specific measuring values or other conditions. This helps to check the correct configuration of the device and connected control units.	9
Selection	<ul><li>Off</li><li>Current output</li><li>Distance</li></ul>	
Factory setting	Off	
Value current output		Â
Navigation	□ Diagnostics $\rightarrow$ Simulation $\rightarrow$ Value curr.out 1	
Description	Defines the value of the simulated output current.	
User entry	3.59 to 22.5 mA	
Factory setting	3.59 mA	
Process variable value		æ

Navigation	□ Diagnostics $\rightarrow$ Simulation $\rightarrow$ Proc. var. value
Description	Value of the simulated process variable. Downstream measured value processing and the signal output use this simulation value. In this way, users can verify whether the measuring device has been configured correctly.
User entry	0 to 20 m
Factory setting	0 m

# Index

## 0...9

4 mA value (Parameter)	48
20 mA value (Parameter)	48
A	
Access status tooling (Parameter)	42
Accessories	
Device-specific	34
flange	34
Overview	34
System components	34
Actual diagnostics (Parameter)	53
Administration (Submenu)	50
Advanced setup (Submenu)	42
Application	. 6

## В

Blocking distance (Parameter)
Bluetooth configuration (Submenu) 52
Bluetooth mode (Parameter) 52
Bluetooth <sup>®</sup> wireless technology

## С

-	
Changing velocity (Parameter)	43
Cleaning	32
Communication (Submenu)	52
Configuration of a level measurement	27
Configuring level measurement	27
Confirm access code (Parameter)	50
Confirm distance (Parameter)	41
Current output (Submenu)	47

## D

Damping output (Parameter)
Define access code (Parameter)
Delay time echo lost (Parameter)
Delete previous diagnostic (Parameter)
Designated use
Device information (Submenu)
Device name (Parameter) 55
Device replacement
Device reset (Parameter) 50
Device tag (Parameter) 39
Diagnostic event
In the operating tool
Diagnostics (Submenu) 53
Diagnostics echo lost (Parameter)
Disposal
Distance (Parameter)
Distance unit (Parameter) 39

## Ε

Empty calibration (Parameter)
ENP version (Parameter) 56
Enter access code (Parameter)
Evaluation distance (Parameter)
Evaluation sensitivity (Parameter)

Extended order code 1 (Parameter)	55
Extended order code 2 (Parameter)	55
Extended order code 3 (Parameter)	55
Exterior cleaning	32

# F

Field of application	
Residual risks	. 6
Firmware version (Parameter)	55
First Echo sensitivity (Parameter)	43
Free field special (Parameter)	51
Full calibration (Parameter)	39

## L

Level (Parameter)	40
Level correction (Parameter)	44
Level linearized (Parameter)	45
Linearization type (Parameter)	45

## М

Maintenance
Mapping end point (Parameter)
Media
Menu
Setup

## 0

Operational safety	. 7
Order code (Parameter)	56
Output current (Parameter)	47
Output mode (Parameter)	43

## Ρ

Post-connection check	20
Present mapping (Parameter)	41
Previous diagnostics (Parameter)	53
Process variable value (Parameter)	57
Product safety	. 7

### R

Repair concept	33
Replacing a device	33
Requirements for personnel	. 6
Return	33

# **S**

Safety instructions		
Basic		6
Safety settings (Su	omenu)	ŧб
Serial number (Par	ameter) 5	56
Setup (Menu)		39
Signal quality (Par	ameter)	53
Simulation (Param	eter)	57
Simulation (Subme	nu)5	57
Submenu		
Administration	5	50
Advanced setur	)	ŧ2

Bluetooth configuration	52
Communication	52
	) <u>_</u>
	Ψ./
Device information	55
Diagnostics	53
Safety settings	46
Simulation	57
System components	34

## Т

8
£9
£9
0
7

## U

Use of the measuring devices
Borderline cases
Incorrect use
Using measuring device
see Designated use

## V

Value current output 1 (Parameter)	57
W	
Workplace safety	7

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